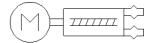
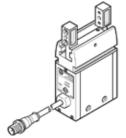
parallel gripper EHPS-25-A Part number: 8070830







Data sheet

Feature	Value
Size	25
Stroke per gripper jaw	16 mm
Max. replacement accuracy	<= 0.2 mm
Max. angular gripper jaw backlash ax,ay	0.3 deg
Max. gripper jaw backlash Sz	0.04 mm
Rotationally symmetrical	<= 0.2 mm
Repetition accuracy, gripper	<= 0.01 mm
Number of gripper fingers	2
Assembly position	Any
Gripper function	Parallel
Design structure	Worm gear unit
	T-shaped
	Rack and pinion
	Electric gripper
Conforms to standard	IEC 61010-1
Guide	Plain-bearing guide
Position detection	For proximity sensor
Motor type	DC servo motor
Control elements	Latched switch
Ready status display	LED LED
Max. cycle frequency	0.8 Hz
Max. cycle frequency Max. current consumption	2 A
Nominal operating voltage DC	24 V
Permissible voltage fluctuation	+/- 10 %
Authorisation	RCM Mark
KC mark	KC-EMV
CE mark (see declaration of conformity)	to EU directive for EMC
	in accordance with EU RoHS directive
Corrosion resistance classification CRC	1 - Low corrosion stress
Sound pressure level	<= 70 dB(A)
Protection class	IP40
Ambient temperature	5 60 °C
Mass moment of inertia	5.24 kgcm2
Max. force on gripper jaw Fz static	450 N
Max. torque at gripper Mx static	28 Nm
Max. torque at gripper My static	16 Nm
Max. torque at gripper Mz static	28 Nm
Lubrication interval for guide components	2 Mio SP
Max. ground per external gripper finger	230 g
Product weight	904 g
Electrical connection	Cable with plug
	M12x1
	5-pin
Mounting type	Optional
mounting type	Internal thread and centring sleeve
	With through-hole and centring sleeve
Materials note	Conforms to RoHS
Material housing	Anodised aluminium
Material gripper jaws	
material gripper Jaws	High alloy steel, non-corrosive